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Optimum satellite remote sensing of the marine carbonate system using empirical
 algorithms in the Global Ocean, the Greater Caribbean, the Amazon Plume and the
 Bay of Bengal

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26 Research highlights

- Satellite salinity measurements enable estimation of surface carbonate parameters.
- Uncertainties within these observation-based estimates are well characterized.
- Monthly satellite salinity and temperature allows synoptic monitoring.
- Satellite observations allow study of seasonal, interannual and episodic variations

32 Abstract

Improving our ability to monitor ocean carbonate chemistry has become a priority as the 33 ocean continues to absorb carbon dioxide from the atmosphere. This long-term uptake is 34 35 reducing the ocean pH; a process commonly known as ocean acidification. The use of satellite Earth Observation has not yet been thoroughly explored as an option for routinely 36 observing surface ocean carbonate chemistry, although its potential has been highlighted. We 37 38 demonstrate the suitability of using empirical algorithms to calculate total alkalinity (A_T) and total dissolved inorganic carbon (C_T), assessing the relative performance of satellite, 39 40 interpolated in situ, and climatology datasets in reproducing the wider spatial patterns of these two variables. Both A_T and C_T in situ data are reproducible, both regionally and 41 globally, using salinity and temperature datasets, with satellite observed salinity from 42 43 Aquarius and SMOS providing performance comparable to other datasets for the majority of case studies. Global root mean squared difference (RMSD) between in situ validation data 44 and satellite estimates is 17 μ mol kg⁻¹ with bias < 5 μ mol kg⁻¹ for A_T and 30 μ mol kg⁻¹ with 45 bias $< 10 \mu mol kg^{-1}$ for C_T. This analysis demonstrates that satellite sensors provide a 46 credible solution for monitoring surface synoptic scale A_T and C_T. It also enables the first 47 demonstration of observation-based synoptic scale A_T and C_T temporal mixing in the 48 49 Amazon plume for 2010-2016, complete with a robust estimation of their uncertainty.

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- 51

52 Keywords

53 Carbonate chemistry; Earth observation; Ocean acidification; Total alkalinity; Dissolved
54 inorganic carbon; SMOS; Aquarius; CORA; HadGEM2-ES

55 1. Introduction

The oceans play an important role in absorbing carbon (e.g. Sabine et al., 2004), and the 56 increase in CO₂ emitted into the atmosphere as a result of anthropogenic activities has 57 resulted in an increase in CO₂ uptake by the oceans (Caldeira and Wickett, 2005; Sabine et 58 al., 2004; Takahashi et al., 2009). This long-term absorption results in a shift in ocean 59 carbonate chemistry, which has the potential to alter biogeochemical cycles and ecosystem 60 61 function in the future (Raven et al., 2005; Kroeker et al. 2013). As a result of the decrease in ocean pH arising from these shifts (often termed Ocean Acidification), this change in ocean 62 63 carbonate chemistry has received increasing scientific and political attention over the past decade. This has led to questions about the magnitude and importance of spatial and temporal 64 ocean carbon variability, as well as how to monitor ongoing change at global and regional 65 66 scales. To-date, carbonate system monitoring has been primarily from ship- and field-based observations that provide relatively disparate and sparse datasets of carbonate chemistry 67 parameters in both space and time. To expand capabilities, state-of-the-art autonomous in situ 68 69 tools are needed (Byrne, 2014). Recent advances include pH sensors on biogeochemical floats (e.g. Johnson et al., 2017), and sensors to observe multiple carbonate system 70 parameters in situ are now in development (Bushinsky et al., 2019). One such advancement is 71 72 utilizing Earth Observation (EO) satellites to provide wider spatial and temporal coverage of surface carbonate chemistry observations, with the aim of detecting features and 73 74 characterizing dynamics that are difficult to resolve using *in situ* datasets (Land *et al.*, 2015; Salisbury et al., 2015; Fine et al., 2017). Currently, there are just two satellites in orbit that 75 are specifically designed to support global carbon cycle research (The US NASA Orbiting 76 Carbon Observatory OCO-2 (Osterman et al. 2016), and the Chinese Tansat; Yang et al. 77 2018), but their focus is to observe and monitor atmospheric CO₂. However, there is a suite 78 of ocean observing satellite sensor datasets that could be used, through exploitation of 79

80 empirical relationships, to provide measures of marine carbonate chemistry parameters that 81 include total alkalinity (A_T), total dissolved inorganic carbon (C_T), partial pressure of CO₂ in 82 seawater (pCO₂) and pH (Gledhill *et al.*, 2009).

83

These four primary variables allow the ocean carbonate system to be investigated. In 84 principle, knowledge of at least two of these four, in conjunction with temperature, salinity 85 86 and pressure, allows the remaining variables to be calculated (Dickson and Riley, 1978). The relationships between these variables are principally driven by thermodynamics; temperature, 87 88 pressure and salinity are therefore fundamentally associated with the carbonate system 89 (Dickson, 2007). Furthermore, salinity is a significant driver of the ionic composition of seawater and hence has a strong relationship with A_T (Millero et al., 1998). In addition to 90 91 these physical controls on the carbonate system, the variables can be influenced by other 92 chemical processes, including weathering and carbonate formation/dissolution (Friis et al., 2003), and biological processes such as primary production, respiration, calcification and 93 94 remineralization (Smith et al., 1975). With this knowledge it is possible to determine how the carbonate system variables vary in relation to factors such as temperature, salinity, nitrate or 95 chlorophyll (the latter two as proxies for biological processes). These relationships take the 96 form of empirical algorithms, which can be used to derive the respective carbonate system 97 variable, and have been developed within a number of global and regional studies, e.g. 98 99 Takahashi et al. (2013); Lee et al. (2006); Lee et al. (2000); Sasse et al. (2013); Cai et al. 100 (2010); Lefèvre et al. (2010); Bonou et al. (2016); see Land et al. (2015) and references therein. 101

102

103 Although initially developed from *in situ* datasets, these empirical algorithms could 104 potentially be forced with inputs from other sources, such as satellite observations or 105 climatologies to yield observation-based carbon system observations. Here we conduct a first assessment of four global algorithms for A_T and three for C_T, utilizing different combinations 106 107 of satellite, interpolated *in situ* and climatology datasets as input. We then evaluate their 108 output using independent in situ measurements of A_T and C_T. As a baseline comparison, we evaluate estimates of A_T and C_T from an Earth System model. In addition to the global 109 algorithms, we also assess three regional A_T and two regional C_T algorithms. We aim to 110 111 demonstrate algorithm suitability both globally and for regional case studies (the Caribbean, the Amazon plume and the Bay of Bengal), and to assess the performance of these different 112 113 approaches, particularly the relevance of satellite datasets, in being able to reproduce the *in* situ patterns of these two carbonate system variables in surface waters. 114

115

116 **2.** Materials and methods

117 2.1. Published algorithms

118 The four global algorithms used here for A_T are from Lee *et al.* (2006) (hereafter referred to 119 as L06), Takahashi and Sutherland (2013) (hereafter referred to as TS13) and Sasse et al (2013) (domain-based and global algorithms, hereafter referred to as S13 and S13g). L06 120 separated the oceans into five domains and used an optimal polynomial fit to AT data, 121 122 resulting in a relationship with sea surface salinity (SSS) and sea surface temperature (SST) for each region. TS13 took this a step further using a larger combination of datasets to 123 124 separate the oceans into 33 domains. Instead of using SST and SSS, TS13 assessed potential 125 alkalinity relationship with SSS, where potential alkalinity is A_T plus nitrate concentration (NO_3) , which corrects A_T for the effect of changes in NO_3 caused by net community 126 127 utilization. Sasse et al (2013) used multiple linear regression to relate domain and global AT to SST, SSS, SSS², dissolved oxygen (DO), silicate (Si) and phosphate (PO₄). The three 128 regional A_T algorithms are all linear relationships with SSS using data from the Amazon 129

plume and Caribbean (Cai *et al.*, 2010; Lefèvre *et al.*, 2010). Two other regional algorithms
(Cooley *et al.*, 2007; Ternon *et al.*, 2000) were considered, but were not used here as results
differed only marginally from Lefèvre *et al.*, (2010) and they used much of the same training
data.

134

The three global C_T algorithms that we used are from Lee *et al.* (2000) (hereafter referred to 135 136 as L00) and Sasse et al. (2013) (domain-based and global algorithms, hereafter referred to as S13 and S13g). L00 found C_T normalized to salinity 35 on the Practical Salinity Scale and 137 138 year 1990, ($nC_T = C_T \times 35 / SSS + (year - 1990$ between 30°S and 30°N)), to be strongly 139 correlated with SST and NO₃, and conducted optimal polynomial fitting for C_T to domain data, giving a total of 12 regionally parameterized equations. Sasse et al. (2013) used 140 141 multiple linear regression to relate domain and global C_T to SST, SSS, DO, NO₃, Si and PO₄. The two regional C_T algorithms are both linear relationships with SSS using data from the 142 Amazon plume (Lefèvre et al., 2010; Bonou et al., 2016). The same two regional studies as 143 for A_T (Cooley et al., 2007; Ternon et al., 2000) were considered for C_T, but again results 144 differed only marginally from those of Lefèvre et al., (2010) and so they were not used. 145 In all cases, extrapolation of algorithms beyond the range for which they were calibrated is 146

questionable, and this is especially true of nonlinear algorithms. To avoid this, we did not use any algorithm outside its specified range of applicability, or more than one SSS unit or SST degree outside its calibration range if a range of applicability is not specified. Table 1 summarises the algorithm choices and dependences. Additional details on each empirical relationship for all algorithms are provided in Supporting Information Text S1.

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153 2.2. Round-robin comparison

154 Four case study regions were used in a round-robin comparison of the algorithms: the global ocean, the Caribbean (14°N to 30°N, 90°W to 60°W for compatibility with Gledhill et al. 155 (2008)), the Amazon plume (2°S to 22°N, 70°W to 32°W), and the Bay of Bengal (5°N to 156 157 24°N, 78°E to 96°E, using the Bay of Bengal International Hydrographic Office Sea Area (International Hydrographic Organization, 1953)). These case studies were chosen as areas 158 that are potentially challenging for this assessment and are discussed in more detail in Land et 159 160 al., (2015). The Amazon region was chosen to enclose the region of freshening contiguous with the mouth of the Amazon with any monthly satellite SSS < 35, with an eastern boundary 161 162 at 32°W, beyond which rain freshening dominates the Amazon plume (Ibánhez et al., 2016). 163 The region defined also includes many points with SSS > 35. To investigate the effect of these points, we also defined a low-salinity Amazon region where data with in situ SSS > 35 164 165 were excluded.

166

Each algorithm was tested using input data for each forcing factor (SSS, SST, NO₃, DO, Si and/or PO₄) from a range of data sources and all possible combinations of inputs were included in the round-robin comparison. The input data for the empirical algorithms were:

170 1) Monthly mean satellite observed data from the Soil Moisture and Ocean Salinity (SMOS)

171 satellite [SSS 2010-2017 CATDS-IFR-CEC-v02] (Reul et al., 2015), the Aquarius satellite

172 [SSS 2011-2015, Version 5] (Le Vine *et al.*, 2014), and the Climate Change Initiative (CCI)

173 [SST 1991-2010] (Merchant *et al.*, 2012);

2) *In situ* re-analysis data from the Coriolis Ocean Re-Analysis (CORA v4.3) database [SSS,

175 SST 1990-2012] (Cabanes *et al.*, 2013);

176 3) Monthly climatology data from the World Ocean Atlas (WOA) dataset [SSS, SST, nitrate,

177 DO, Si, PO₄] (Garcia *et al.*, 2010);

Note that WOA 'nitrate' is actually nitrate + nitrite (NO₃ + NO₂). However, NO₂ typically has a concentration at least an order of magnitude lower than NO₃, and so this discrepancy is neglected. The previously mentioned baseline comparison dataset were A_T and C_T output from the HadGEM2-ES global Earth system model, 1972-2020 (Jones *et al.*, 2011) (hereafter referred to as HG2).

All data were binned spatially to a $1^{\circ}x1^{\circ}$ grid and temporally to monthly intervals (henceforth referred to as monthly data). The multi-year CORA, satellite and HG2 data were also each combined to form monthly climatologies (climatological data). Only $1^{\circ}x1^{\circ}$ grid cells with at least two values were used to calculate climatological data. Details of all of these input datasets are provided in Table 2.

188

189 The binned A_T or C_T from each algorithm and input, herein referred to as 'output', and the 190 binned output from HG2 were all evaluated (validated) against binned in situ data of the respective carbonate parameter. Data from the Global Data Analysis Project Version 2 191 192 (GLODAPv2, 1972-2013) (Olsen et al., 2016) were the primary in situ evaluation 193 (validation) data used for both A_T and C_T evaluations, along with some additional regional in situ data (see Table 3). The GLODAPv2 dataset is a community compiled, merged and 194 internally consistent global dataset. In all cases of *in situ* data, the mean measurement in the 195 196 top 10 m water depth was used.

197

Following (Sasse et al. 2013), we attempted to separate the effects of terrigenous influences and sediment resuspension on the biogeochemistry of coastal waters from open ocean carbonate chemistry by calculating the minimum depth within each cell using the GEBCO_08 one-minute grid (www. gebco.net/

202 data and products/gridded bathymetry data/gebco one minute grid/, downloaded on December 14th, 2009) and repeating our analysis using only grid cells with minimum depth 203 greater than 500 m. Again following (Sasse et al. 2013), we further separated terrigenous 204 205 effects by calculating the minimum distance from the nearest coast within each cell using (https://oceancolor.gsfc.nasa.gov/docs/distfromcoast/, downloaded on October 5th, 2018) and 206 repeated the analysis using only grid cells with both a minimum depth greater than 500 m and 207 208 a minimum distance greater than 300 km. All three sets of results are included in Supplementary Information, but only data with both masks applied are presented here. 209

210

211 2.3. Statistical measures

212 2.3.1 Data uncertainties

213 The GLODAPv2 analysis (Olsen et al., 2016), the chosen reference validation dataset, includes an estimate of the maximum bias that exists between different instruments 214 determined via a crossover analysis as 4 and 6 μ mol kg⁻¹ for C_T and A_T respectively. Whereas 215 216 a full uncertainty budget (i.e. a type A uncertainty estimate (BIPM, 2008) comprising a combination of bias and standard deviation of all measurements against a traceable standard) 217 are not provided. Therefore in the absence of all components of the uncertainty information 218 we assume nominal uncertainties of 0.5% for all in situ A_T and C_T (Bockmon et al., 2015). It 219 should be noted that due to relatively recent improvements in quality control we would 220 221 expect older in situ measurements to have greater uncertainties and more recent 222 measurements to have lesser, though this variation is difficult to quantify. For interest, the GLODAPv2 bias estimate stated above for a mean global A_T of 2450 µmol kg⁻¹ gives a 223 potential bias around 0.2%. Uncertainties in the input (forcing) data (SST, SSS, NO₃ and 224 HG2 A_T and C_T) were not included in our analysis, since these are unknown for many of the 225 input datasets. For interest only, the reported uncertainty in SMOS SSS is below ± 0.3 for a 30 226

day average over a 100×100 km open ocean area (Reul *et al.*, 2012; Reul *et al.*, 2014) and can be below ± 0.2 for an 18 day average (Boutin *et al.*, 2018) or in certain evaporationdominated regions, and for Aquarius SSS it is ± 0.17 for a monthly average over a 150×150 km open ocean area (Lagerloef *et al.*, 2015). Uncertainty in CCI SST is between ± 0.1 and ± 0.15 K (Merchant *et al.*, 2014). However, we could find no uncertainty estimates for the CORA, WOA or HG2 datasets, and it would be inconsistent to apply uncertainties to some inputs and not others. We discuss the impact of this approach within Section 4.2.

234

The published algorithm uncertainties (as stated in the corresponding reference) for each algorithm were propagated through to the algorithm outputs. Following standard propagation methods (Taylor, 1997), *in situ* and algorithm uncertainties were combined assuming that they were uncorrelated (a sum of squares analysis), allowing weighted statistics to be calculated, with each data point weighted by the inverse of the sum of squared uncertainties.

240

241 2.3.2 Evaluating output accuracy

Output mean (\bar{x}_m) , standard deviation (σ_m) and *in situ* carbonate data mean (\bar{x}_d) and standard deviation (σ_d) were calculated for each assessment, as well as root-mean-square-difference (RMSD), mean absolute difference (MAD), bias and point-to-point correlation (R) between output and the evaluation (GLODAPv2) *in situ* data. As a check, each of these statistics is presented both weighted and unweighted. Unweighted and weighted RMSD values were usually within about 10%, except in the case of global A_T using the TS13 algorithm, which includes regions with very different algorithm errors. Weighted statistics are used hereafter.

249

A potential problem with comparing outputs in this way is that different outputs overlap with different evaluation *in situ* data. Consider the plausible situation in which all outputs perform

poorly in coastal waters. All else being equal, an output that is not evaluated using coastal in 252 situ data will produce better statistics than one that is. Therefore, to compare like with like, in 253 254 each region we considered outputs in pairs, for a given pair calculating RMSD for each of the 255 two outputs using only in situ evaluation matchups shared by both outputs. Each output is given a 'score' of RMSD / RMSD_{min}, 1 for the lower RMSD and ≥ 1 for the other. This is 256 repeated for all possible pairs, then each output is given a 'final score' equal to the mean of 257 258 all of its scores. To convert this to an estimate of RMSD, we chose a representative output as that with the lowest value of (weighted final score / number of matchups), i.e. the output with 259 260 the best combination of performance and coverage. The weighted RMSD of this output (RMSD_{rep}) was left unchanged and all other output weighted RMSDs in the region were set 261 to RMSD_{rep} \times final score / (final score)_{rep}, where (final score)_{rep} is the final score of the 262 263 representative output; this measure is henceforth referred to as RMSDe. Output results can be compared directly within a region, but comparison of output RMSDe between regions or 264 carbonate parameters should be treated with caution. The above calculations could equally be 265 266 done using MAD in place of RMSD, though we have not done this here.

267

268 2.3.2 Evaluating optimal combinations of output elements and importances

To calculate the relative importance of different combinations of output elements (algorithms 269 and/or data inputs) to the output comparison results, we calculated the best RMSDe when a 270 271 given combination is excluded from all outputs, and divided it by the overall best RMSDe to 272 give an RMSDe ratio. For example, the most effective single exclusion, with an RMSDe ratio of 1.022 (i.e. a 2.2% difference), is A_T using climatological CORA SSS in the Bay of Bengal. 273 The best 13 A_T outputs in the Bay of Bengal all use climatological CORA SSS. Conversely, 274 the best output also uses monthly CCI SST but the second best uses WOA SST, so excluding 275 monthly CCI SST has much less effect. Excluding WOA SST has no effect, since the best 276

output is still the one using monthly CCI SST. Having excluded climatological CORA SSS, the next 14 best A_T outputs all use the TS13 algorithm, so excluding climatological CORA SSS and TS13 has the largest effect among pairs of exclusions in this region. All possible combinations of exclusions were considered, ranked in order of number of elements excluded, then by RMSDe ratio.

The resulting comprehensive list is rather hard to read and interpret. To simplify, we created subsets of exclusions objectively considered as most significant. Criteria used were that the RMSDe ratio was greater than 1.01, the exclusions were either all SSS and/or SST inputs or all algorithms, and RMSDe ratio exceeded that of a subset of exclusions by >0.1%. For example, excluding TS13 and SMOS SSS would not qualify, and excluding SMOS and Aquarius SSS would only qualify if its RMSDe ratio were greater than excluding only SMOS and only Aquarius by >0.1%.

289

290 **2.3.3** Comparing between carbonate parameters

To compare between carbonate parameters in each region, we only considered *in situ* evaluation data points where both A_T and C_T values existed. For each data point and parameter, all outputs producing valid output were considered and the one with the best regional final score was chosen, noting the output-*in situ* difference for this output. The regional RMSD of each parameter was then calculated from the differences at all data points in the region.

297

298 **3. Results**

Results are summarized in Figure 1A and B, showing RMSDe for A_T and C_T , Table 4, showing statistics of the lowest-RMSDe output for each SSS source plus HG2 output in each region, and Table 5, showing selected importances. Figures 2 to 4 contain plots of output versus evaluation (GLODAPv2) *in situ* A_T , C_T and SSS data, with points with depth < 500m and > 300 km from the coast labeled. Alternative versions of Figures 1A and 1B for differing masks are shown in Figure S1. Supporting data (Land et al. 2019) consist of three data collections corresponding to all data, minimum depth 500 m, and minimum depth 500 m plus minimum distance to coast 300 km; matchup data, output statistics, details of output score calculations, spatial data results, importances of exclusions and the comparisons between carbonate parameters (also included in Supplementary Information) are included.

309 Generally there is little to choose between the SSS sources (re-analysed *in situ* or satellite) 310 apart from HG2, which performs less well in all regions, or between monthly and 311 climatological SSS sources. The main differences in performance are between algorithms and 312 between regions, but there is no clearly superior algorithm.

313

314 3.1. Total Alkalinity (A_T)

See Table 4 for detailed results. Globally, the best RMSDe values of about 17 μ mol kg⁻¹ are substantially lower than the SD of the global coverage *in situ* data used for the evaluation (81 μ mol kg⁻¹), and in the Amazon and Bay of Bengal they are slightly lower (RMSDe of 55 compared to a SD of 68, and RMSDe of 11 compared to a SD of 16 μ mol kg⁻¹, respectively), but in the Greater Caribbean and low-salinity Amazon the RMSDe are higher than the SD, meaning that none of the tested combinations of algorithms and inputs is accurate enough to distinguish natural variations in A_T in these latter two regions.

322

323 3.1.1. A_T algorithm and input importances

324 See Table 5 for details. Globally, S13 performs slightly less well (higher RMSDe) than other 325 algorithms, as do climatological satellite inputs. In the Greater Caribbean, monthly SMOS 326 and Aquarius and climatological Aquarius SSS perform significantly less well. In the Amazon, the Lefevre et al (2010) algorithm and climatological Aquarius and WOA SSS perform less well. In the low-salinity Amazon, monthly SMOS and Aquarius and monthly CCI SST perform best. In the Bay of Bengal, climatological CORA SSS performs best and climatological Aquarius performs significantly less well.

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332	3.1.2.	A_T summary
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333 For all case study regions and with respect to these empirical outputs, satellite SSS can reproduce in situ measured AT from the GLODAPv2 evaluation dataset with performance 334 335 (RMSDe) comparable to, or better than, the re-analysed in situ data derived inputs for SSS, and the satellite based A_T is always better than HG2 A_T estimates. Globally HG2 336 performance is about 85% worse than the best SSS driven outputs, but this reduces to 15-337 20% in the Amazon plume. Monthly Aquarius and SMOS observations provide a credible 338 solution to monitoring synoptic scale global and regional A_T, though in some challenging 339 regions (Greater Caribbean and low-salinity Amazon plume) none of the tested methods are 340 sufficiently accurate to resolve natural variability. 341

342

RMSDe in the Amazon plume is higher than the global RMSDe, reflecting the larger regional standard deviation in the *in situ* data due to the large gradients around the river flow, and RMSDe in the Amazon with SSS < 35 is higher than in the wider Amazon, but the relative performance of SSS inputs is similar.

Excluding the Amazon plume and HG2, the best outputs have bias less than 5 μ mol kg⁻¹, or 0.2% of the global mean A_T (of 2450 μ mol kg⁻¹) which is similar to the estimated evaluation dataset *in situ* nominal uncertainty of 0.5% (Bockmon *et al.*, 2015) and the inter-annual variability of A_T observed at oceanic sites such as at the Hawaiian Ocean Time-series station (HOT; ±6 μ mol kg⁻¹) (Brix *et al.*, 2004), but lower than the seasonal variability observed at

oceanic sites (20 to 30 µmol kg⁻¹ at both the Bermuda Atlantic Time-series Study (BATS) 352 (Bates et al., 2012) and the European time series station (ESTOC) (Santana-Casiano et al., 353 2007). This seasonal variability at BATS and ESTOC is also greater than the best global 354 RMSDe of 17 µmol kg⁻¹. In the Amazon plume, of the monthly SSS sources only SMOS has 355 low bias (2 µmol kg⁻¹), and in the low-salinity Amazon plume, all SSS sources have bias 356 greater than 19 µmol kg⁻¹. These results highlight that these methods (of using satellite 357 observations or re-analysed in situ dataset as input to empirical algorithms) can obtain 358 measures of AT that are not significantly biased relative to the evaluation in situ 359 360 measurements, except in regions of strong spatiotemporal variability. It also shows that these methods are capable of distinguishing the seasonal variability at long-term time series sites, 361 362 though not the interannual variability at HOT.

- 363
- 364

Total Dissolved Inorganic Carbon (C_T) *3.2*.

See Table 4 for detailed results. Globally, the best RMSDe values of 29-30 µmol kg⁻¹ are 365 considerably higher than the equivalent global A_T RMSDe values, but still substantially 366 lower than the SD of the global in situ evaluation dataset (69 µmol kg⁻¹), and in the Amazon 367 and Greater Caribbean they are similar (RMSDe 45 compared to SD 53 and RMSDe 19 368 compared to SD 18 µmol kg⁻¹, respectively), but in the low-salinity Amazon and Bay of 369 Bengal they are higher, meaning that no combination of algorithms and inputs is accurate 370 371 enough to distinguish natural variations in C_T in these latter two regions.

3.2.1. C_T algorithm and input importances 372

See Table 5 for details. Globally, L00 and S13g perform better (lower RMSDe) than other 373 algorithms, as do CORA, WOA and monthly SMOS SSS inputs. In the Greater Caribbean, 374 the S13g algorithm performs very poorly and climatological Aquarius SSS performs less well 375 than other SSS inputs. In the Amazon, the S13g algorithm and Aquarius SSS perform less 376

well. In the low-salinity Amazon, the S13g algorithm performs less well, while SMOS,
Aquarius and monthly CCI SST perform best. In the Bay of Bengal, the S13 and S13g
algorithms perform considerably better than other algorithms and CORA and WOA SSS
perform better than other SSS sources.

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382	3.2.2.	C_{T}	summary
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383 Similar to A_T, satellite inputs for SSS can reproduce the C_T data (from the GLODAPv2 evaluation dataset) with similar ability, and sometimes better than using re-analysed or 384 385 climatology in situ derived SSS inputs, except for Aquarius in the Amazon plume (Figure 1B), and always better than HG2 C_T estimates. Global HG2 performance is only about 14% 386 worse than the best SSS driven outputs, but this increases to over 80% in the Bay of Bengal 387 and Greater Caribbean. As with AT, monthly SMOS and Aquarius observations provide a 388 credible solution to monitoring synoptic scale global and in some cases regional C_T. Best 389 RMSDe values are higher for C_T than A_T globally and in the Greater Caribbean and Bay of 390 Bengal, but lower in both Amazon plume regions. Again, in some challenging regions (low-391 salinity Amazon plume and Bay of Bengal), none of the tested methods are sufficiently 392 393 accurate to reproduce natural variations.

394

Bias in the C_T outputs is generally greater and more variable than that in the A_T outputs, except in the Amazon plume where non-HG2 monthly and climatological bias is uniformly less than 3 µmol kg⁻¹. The smallest bias among the best global monthly outputs is monthly CORA with -9 µmol kg⁻¹, in the Greater Caribbean monthly SMOS and Aquarius have bias of 3 and 4 µmol kg⁻¹ respectively, monthly outputs in the low-salinity Amazon are all strongly biased, the smallest being CORA with 45 µmol kg⁻¹, and in the Bay of Bengal monthly CORA has bias of 16 µmol kg⁻¹ while climatological datasets (WOA, CORA,

402	SMOS) have lower bias (-11, -12, -14 μ mol kg ⁻¹ respectively). For comparison, the <i>in situ</i>
403	nominal uncertainty of 0.5% (Bockmon et al., 2015) at the global average C _T of 1900 µmol
404	kg ⁻¹ would be 9.5 μ mol kg ⁻¹ , the inter-annual variability of nC _T is ±4 μ mol kg ⁻¹ at HOT and
405	±8 µmol kg ⁻¹ at ESTOC (Brix et al., 2004, Santana-Casiano et al., 2007), while the seasonal
406	amplitude of nC_T at HOT is 15 µmol kg ⁻¹ (Brix <i>et al.</i> , 2004) and those of C_T at ESTOC and
407	BATS are 20-30 and 40-50 µmol kg ⁻¹ , respectively (Santana-Casiano et al., 2007, Bates et
408	al., 2012). The biases in these outputs are also comparable to the systematic biases found by
409	Lee et al. (2000) when comparing algorithm derived nC_T to nC_T calculated from A_T and
410	pCO ₂ data (-3 to +15 μ mol kg ⁻¹). Thus, these results highlight that some of the outputs
411	evaluated can obtain measures of C _T that are not significantly biased relative to the <i>in situ</i>
412	evaluation measurements, though overall uncertainties may be high relative to the variability
413	at these long-term monitoring sites.

415

5 3.3. A_T and C_T Algorithm biases

In the Amazon Plume, the best output was strongly correlated with the evaluation *in situ* A_T or C_T , but with a slope significantly different from 1 (Figures 2B and 3B). Replacing monthly satellite SSS with monthly or climatological CORA SSS (re-analysed and interpolated *in situ*) produces similar biases (Figure 4), suggesting that the cause of the bias is not specific to satellite SSS or monthly data.

421

422 A possible explanation of this bias would be that the algorithm is not capturing the two 423 endmember mixing from the river with zero salinity and some finite, but significant A_T and 424 C_T . However, the regional algorithms for the Amazon plume implicitly include the river 425 endmember, as they are based on measurements that include low and high salinity values, 426 and each published algorithm finds a strongly linear relationship between salinity and A_T or 427 C_T. Since the bias using these algorithms is similar to that using the global algorithms, we can
428 conclude that the endmember issue is not the main reason for the bias.

429

430 Another possible explanation of the bias would be sampling of water with low SSS, A_T and C_T in regions with high spatial and temporal SSS variability, as found in the Amazon plume 431 and particularly within the low salinity Amazon plume region. Satellite and CORA data 432 represent an average over at best one grid cell (about 10^4 square kilometers at the equator) 433 and one month (or the same month in a range of years in the case of climatological data), 434 435 while an in situ measurement samples a very small volume of water and is almost instantaneous. The effect of this averaging is to remove variability that occurs on smaller 436 spatial and temporal scales. For example, low *in situ* salinity in the Amazon plume may be 437 438 caused by small eddies or filaments of river water not resolvable at the grid cell scale, or by 439 interannual variations in the plume extent. In this situation, extreme evaluation in situ values will consistently be matched with outputs driven by satellite and CORA data that are closer to 440 441 the large-scale and long-term mean. If the salinity distribution is strongly one-tailed, as in the Amazon plume, and the cause of anomalies is consistently unresolved by the averaged data, 442 the in situ evaluation data will consistently give lower salinity than the averaged data, as 443 observed here (Figure 5). This issue is likely to be one cause of the large biases evident in all 444 445 output results (re-analysed in situ and satellite input derived) for the low salinity Amazon 446 region.

447

A third possible explanation for the bias arises from fundamental differences between the *in situ* measurements used to calibrate the original algorithms and the satellite salinity observations used herein as input to the algorithms. Satellite SSS observations represent the conditions in the top 10 mm of the water (Boutin *et al.*, 2013), whereas *in situ* SSS

observations are typically sampled from ≥ 1 m below the surface. This can result in 452 geophysical sources of variation between satellite and *in situ* salinity, which are linked to 453 vertical salinity stratification, and these features are prevalent in regions of rain, oceanic 454 455 fronts and river outflow (Boutin et al., 2013; Boutin et al., 2016; Drucker et al., 2014). For example, salinity gradients created by freshwater plumes can complicate the comparison of 456 satellite and *in situ* salinity measurements; a difference of 2–5 pss m⁻¹ has been observed 457 across the halocline in the Amazon plume (Lentz et al., 1995). Plumes can also cause 458 horizontal salinity gradients with spatial scales smaller than the footprint of the satellite 459 460 radiometers. Typical horizontal SSS gradients for the plumes from the Amazon (Lentz et al., 1995) or Congo (Chao et al., 2015) exceed 0.2 pss km⁻¹ and extend more than 250 km from 461 the river mouth. Therefore, in the vicinity of a river plume, a spatially sparse array of *in situ* 462 463 sensors can exhibit very different SSS variability from that observed by a satellite sensor, 464 even if the measurements are all coincident. Similarly, high-frequency SSS variations (e.g. tidal effects) can be undersampled by satellite-derived SSS products due to the relatively long 465 466 revisit time of the satellite (2–3 days for SMOS and 7 days for Aquarius). Accounting for the depth-related differences should increase the accuracy of the outputs, and a rigorous 467 treatment might adapt the theory currently used to reconcile in situ and satellite SST 468 (Merchant et al., 2014). We therefore recommend that the satellite SSS community consider 469 investigating this theory for SSS. 470

471

In the absence of a rigorously tested explanation for these biases, and to demonstrate the potential gain from reducing them, we simply note that linear regression of the best output against the evaluation *in situ* A_T and C_T reduces the RMSD (actual, not estimated) in the low salinity Amazon plume region from 215 to 48 µmol kg⁻¹ (a 77% reduction) for A_T and from 67 to 50 µmol kg⁻¹ (26%) for C_T .

478 3.4. Comparison of A_T with C_T

Results are shown in Dataset S23, showing that in direct comparisons at each matchup position, the A_T outputs have a 42% lower RMSDe than C_T globally, 41% lower in the Bay of Bengal and 21% lower in the Caribbean, indicating that A_T outputs can generally be retrieved more successfully than C_T outputs. However, A_T has a 13% higher RMSDe than C_T in the Amazon and 9% higher in the low salinity Amazon using the same algorithms as in the global case, so this relationship is not universal.

485

486 3.5. Multi-year synoptic observations

The methods evaluated here enable the first multi-year synoptic scale observations of A_T and 487 C_T spatial mixing and distributions. To demonstrate their application we characterise the 488 synoptic scale, extent and influence of river-flow-dominated alkalinity mixing in the Amazon 489 plume and western North Atlantic. The Amazon Plume exhibits a two-end-member 490 491 alkalinity-salinity mixing regime, resulting in a strong linear relationship between alkalinity and salinity (Cai et al., 2010), and mixing between river water and seawater is the dominant 492 493 controlling factor of the alkalinity-salinity relationship in the western North Atlantic (Jiang et al., 2014). The accuracy assessment means that we can illustrate SMOS or Aquarius 494 observational-based C_T and A_T monitoring of the Amazon plume along with a calculated 495 496 estimate of the combined uncertainty in C_T and A_T (provided by the RSMDe and bias).

497

To simplify the interpretation we present results using the same algorithm for monthly SMOS and Aquarius, so that any differences are due solely to the SSS source. For A_T , the best output with both SMOS and Aquarius is TS13 with WOA nitrate, with RMSDe of 57.7 µmol kg^{-1} for SMOS and 58.4 µmol kg^{-1} for Aquarius. For Ct the best Aquarius outputs use 502 different algorithms to the best SMOS outputs, and perform less well. Therefore for 503 simplicity we present results of using SMOS and Aquarius with a single algorithm and input 504 pairing (L00 and climatological CORA SST), with RMSDe of 45.0 μ mol kg⁻¹ for SMOS and 505 52.2 μ mol kg⁻¹ for Aquarius. We calculated A_T and C_T time series for the Amazon plume 506 using the above algorithm and input pairings, producing monthly Aquarius and SMOS 507 derived A_T and C_T collectively covering the time period 2010 to 2016.

508

Figure 6 shows the regional (0-15°N, 45-62°W) mean SMOS and Aquarius SSS, 509 510 climatological CORA SST, output A_T and output C_T, in relation to climatological Amazon discharge data from the Obidos gauge located 750 km from the ocean (Perry et al., 1996). 511 The discharge data are only provided as an indication of variations in Amazon discharge and 512 513 will not represent the total flow (Salisbury et al., 2011). In a given month with both SMOS 514 and Aquarius data, we calculate mean SSS using only cells in which both have valid data, in order to compare like with like. If this is not done, and one dataset extends into a low salinity 515 516 region not covered by the other, large spurious differences can occur, e.g. in May 2014 inconsistent masking causes the regional mean Aquarius SSS to be 1.24 units lower than 517 SMOS SSS (results not shown), a difference that reduced to 0.07 units with consistent 518 masking. Maximum SSS consistently occurs during December and January and minimum 519 SSS occurs during May-July, 1-3 months after the maximum discharge in April, both of 520 521 which are consistent with previous findings (Salisbury et al., 2011). As expected, A_T and C_T 522 maxima occur in phase with the variations in SSS, and typically lag the peaks in SST by one to two months, with regional A_T each year varying between 2230 and 2370 µmol kg⁻¹ and C_T 523 524 varying between 1890 and 2000 µmol kg⁻¹.

Figure 7 reveals the seasonal patterns in A_T over the same period as shown in Figure 6B in 526 relation to the dynamics of the Amazon discharge and their interaction offshore with the 527 528 along-shore North Brazilian Current, North Equatorial Counter Current and Guyana Current. The August 2011 SSS conditions are shown in Figure 7A. Clear annual cycles and river 529 plume features are apparent in the observed A_T, with the Amazon plume influencing A_T more 530 than 1000 km offshore of the mouth of the Amazon (Figure 7B-D). During June-July each 531 year, very low A_T values reaching below 2100 µmol kg⁻¹ are apparent at the mouth of the 532 Amazon (Figure 7D), the timing of which is consistent with the observed annual minima in 533 534 SSS (Salisbury et al., 2011) (see also Figure 6). Further west the river plume spreads out as it interacts with the along-shore currents, resulting in A_T in the region of ~2150 µmol kg⁻¹ up to 535 ~1700 km offshore (regions of yellow up to ~17°N in Fig. 3C). The Amazon plume has been 536 537 observed to bifurcate during the northern hemisphere summer months (Del Vecchio et al., 2004), with one part of the river plume heading north-west and a second jet retroflected to the 538 east (Salisbury et al., 2011). This bifurcation is apparent each year around August (Figure 539 7A-D), with an isolated feature of A_T around 2000-2100 µmol kg⁻¹ appearing 500-1000 km 540 offshore and to the east of the river mouth, although this feature was less pronounced during 541 2014 (regions of yellow between 5-10°N in Figure 7D). 542

543

Figure 8 shows Aquarius and SMOS monthly A_T for April 2012 overlaid with 100 *in situ* A_T observations from the GLODAPv2 dataset (Olsen *et al.*, 2016) collected at 3 m nominal depth during 13 consecutive days in April and May 2012, and Figure 9 shows the equivalent plot for C_T . Despite the different temporal resolutions, the change in magnitude of the observations (the gradient) between the open ocean data and those close to, and within the river plume, are generally comparable to the synoptic scale observations. The high monthly temporal variations along the ~52°W latitudinal transect are illustrated in Figure 7D. The

differences between in situ and synoptic scale observations are discussed in section 3.3. This 551 comparison highlights the power of the synoptic scale observations, allowing the *in situ* 552 553 observations to be placed within their wider spatial and temporal context. It also highlights how the synoptic observations characterise the distributions and mixing at the very surface of 554 the water column and how these can be different from that observed in situ (at a nominal 555 depth of 3 m), particularly in regions of strong river plume influence. Figures 8 and 9 could 556 557 suggest that lower values of A_T and C_T are found below the surface in the coastal region, whereas offshore the salinity, A_T and C_T are vertically well mixed. A combination of *in situ* 558 559 and synoptic scale observations could be used to understand the near-surface vertical profile of A_T. 560

561

562 **4.0 Discussion**

563 **4.1 Bay of Bengal**

Because there are permanent and strong radio-frequency interference sources around the 564 565 coasts of Asia, SSS measurements from SMOS and Aquarius are likely to be of a lower quality in the Bay of Bengal. However, the paucity of in situ measurements in the Bay of 566 Bengal in the satellite salinity era makes comparison difficult. The Bay of Bengal in situ AT 567 data measured in 2014 were not included in the main analysis due to their proximity to the 568 coast (and so were removed due to the masking), and their inclusion causes the RMSDe of 569 HG2 to increase to over 600 µmol kg⁻¹ (Figure S1). This demonstrates the importance of 570 comparing like with like when evaluating the outputs and also highlights the influence of 571 focusing on evaluation data without terrigenous influence. The low number of in situ data 572 points used in the Bay of Bengal accuracy assessment highlights that the evaluation of output 573 datasets (from both satellites and re-analysed in situ) will be biased against small-scale 574 variability that may be captured by the in situ observation data used for the evaluation, 575

576 particularly when in situ validation sites are relatively near-shore and the effect of riverine water flow is more pronounced. This was the case for the 2014 in situ dataset that was 577 578 omitted from the main accuracy assessment due to falling within the masked area: the site 579 was part of the Sundarbans Biological Observatory Time Series, representing the coastal part of the Sundarbans mangrove ecoregion, which can act as a source and a sink of CO₂ during 580 pre-monsoon (April-May) (Akhand et al., 2017), and it is also an area that receives high 581 freshwater discharge (~42000 m³ s⁻¹) along with local heavy seasonal precipitation, in 582 addition to increasing anthropogenic pressure (Choudhury et al., 2015). The other case study 583 584 regions have more data available for comparison and therefore this variability may be averaged out in the *in situ* data binning process. It is essential that more *in situ* carbonate 585 system data are collected to elucidate these issues for this complex region (the Bay of 586 587 Bengal), which has a strong riverine influence, and to characterize the variability on a wider scale than has currently been observed (Sarma et al., 2012; Samanta et al., 2015). 588

589

590 A large area of the Bay of Bengal is characterized by pCO₂ levels far below the atmospheric value (i.e. a large gradient between atmospheric and oceanic pCO_2), which is more prominent 591 during the north-east monsoon when the air-sea pCO₂ gradient exceeds 100 µatm (Akhand et 592 al., 2013; Ganguly et al., 2011). The enhanced gradient is possibly due to new biological 593 production sustained by excessive nutrient inputs from the Ganga-Brahmaputra-Meghna river 594 595 basins, thus influencing the carbonate system via net organic production. Additionally, the 596 presence of non-carbonate alkalinity in these regions (e.g. riverine contributions of organic 597 species including humic acid) can result in A_T that is not correlated with salinity (Akhand et 598 al., 2013). Only 14 of the outputs overlapped in space and time with the 2014 in situ data that 599 captured this very near-shore variability, resulting in the apparent poor performance of these 14 outputs before coastal masking. If the other outputs had also captured this near-shore 600

variability they may also have had reduced performance. Low satellite SSS coverage due to the issues of radio-frequency interference described above will have also contributed to lower performance of the satellite data driven outputs in this region. Improvements in satellite data coverage in coastal regions together with increased *in situ* data are likely to begin resolving these issues.

606

607 **4.2 The need for continued efforts in quantifying uncertainties**

The problem of uncertainties, and their propagation through the analysis, is an ongoing one. 608 609 Here, the estimated uncertainties in the in situ measurements used for the evaluation and 610 algorithm uncertainties were included in the analysis where they were quantifiable (i.e. nominal uncertainties for the C_T and A_T in situ evaluation measurements and the propagation 611 612 of the empirical algorithm uncertainties). Published remote sensing uncertainties are available, however no such information exists for the other input datasets; and even within 613 the carbonate system there are still many challenges to fully defining *in situ* and laboratory 614 615 measurement uncertainties (Andrew Dickson, pers. comms.; Bockmon and Dickson, 2015). Therefore, quantification of associated uncertainties for all of the input data sources requires 616 continued work. Furthermore, unavoidably in this analysis, data used to evaluate the 617 algorithm outputs were unlikely to be wholly independent from the data used to create the 618 algorithms. In order to have a fully independent evaluation dataset, original datasets would be 619 620 required to develop the algorithms whilst keeping enough data separate from the algorithm 621 development process to enable an independent evaluation. This was not possible in this initial assessment due to the general dearth of measurements in some regions, and due to ambiguity 622 623 over which measurements were used to develop the historical algorithms.

However in relation to our calculated combined uncertainties of our outputs, the estimated combined uncertainties from Fine *et al.* (2017) of smaller than $\pm 20 \ \mu\text{mol kg}^{-1}$ for retrieving global A_T using satellite salinity and SST are consistent with our global results of RMSDe of 17 μ mol kg⁻¹, bias < 5 μ mol kg⁻¹. This gives further confidence in the approach taken here. We note however that Fine *et al.* (2017) misinterpreted the uncertainty information provided by Olsen et al., (2016), as Olsen *et al.* only state the bias, which as previously discussed is only one component of a Type A uncertainty.

632

To test the sensitivity of the output uncertainties to the SST and SSS satellite remote sensing 633 input data uncertainties, the latter were propagated through the analysis for all global 634 635 empirical A_T algorithms (TS13, Lee06, Lee00, S13, S13g) for two example months (January and July). This results in A_T output uncertainties (due solely to satellite SSS and SST input 636 637 data) of 0.2 to 0.8% (Table 6), which is close to the nominal *in situ* uncertainties of 0.5%, or ± 10 umol kg⁻¹. The combined uncertainty in most of the studied regions is considerably 638 greater than this, implying that (in the global case at least) the other components of the 639 640 uncertainty budget dominate over the remote sensing input data uncertainty.

641

642 **4.3** The need for algorithm retraining and the collection of *in situ* observations

Only seven global and five regional algorithms were presented here, in addition to output of A_T and C_T from HG2, primarily because these were the only algorithms from the published literature that did not require additional re-parameterization for all the case study regions. Future efforts are needed to perform this re-fitting, not only for additional A_T and C_T algorithms, but also for the remaining carbonate system parameters (pCO₂ and pH). This is a demanding task; with just the 14 algorithms and model outputs used here, 1070 outputs were compared in the round-robin comparisons. Further, where few *in situ* measurements of a 650 carbonate variable exist (e.g. pH), information could be obtained for future assessments by calculating this variable from two of the other carbonate variables (e.g. C_T and A_T) along with 651 652 temperature and salinity. Calculating the variable in this way does introduce additional uncertainties, thus to be truly beneficial, such outputs should include the propagation of all 653 uncertainties. A future assessment of the exploitation of satellite SSS will require further 654 analysis of temporally resolved (rather than climatological) satellite observations, using new 655 656 in situ data. We found only three cruises within GLODAPv2 that overlap with satellite salinity observations in our regions: none in the Bay of Bengal, one in the Amazon plume at 657 658 the beginning of May 2010 (the first month of reliable SMOS data after its launch in November 2009) and two in the Amazon plume in April and May 2012 (shown in Figures 8 659 and 9), one of which overlapped with the Greater Caribbean (only 6% and 3% of the 660 661 GLODAPv2 data correspond to SMOS and Aquarius eras respectively). Hence coverage where we have both *in situ* and satellite observations is very limited spatially, seasonally and 662 663 interannually, highlighting the need for further in situ data. It should also be noted that the lowest uncertainties achieved using these satellite observation-based and empirical 664 approaches are still greater than the nominal *in situ* and laboratory measurement uncertainties 665 (of $\pm 10 \text{ }\mu\text{mol }kg^{-1}$) so the methods presented here are unlikely to ever be a substitute for *in* 666 situ measurements. Their strength is in providing synoptic data to fill the inevitable gaps in 667 the *in situ* data coverage. To enable all new *in situ* data to be fully exploited by the Earth 668 observation community they need to have been collected following international protocols (as 669 defined by Dickson et al., 2007), analysed using traceable standards (as advocated by 670 Bockmon and Dickson, 2015) enabling the provision of a complete uncertainty budget 671 (quantified as a Type A uncertainty, BIPM, 2008). If possible, the historical data contained 672 within the GLODAPv2 dataset would benefit from the inclusion of some indication of their 673 uncertainty budget e.g. a simple 'high', 'low' or 'unknown' determined using existing 674

675 metadata and/or expert interpretation and opinion via a Type B uncertainty approach as 676 defined by BIPM, (2008). Similarly, the CORA re-analysis and WOA climatology data 677 would benefit from similar additions as these datasets lack any uncertainty information.

678

679 **4.4 Earth system model performance**

It should be noted that we would not expect a free running global Earth system model such as HG2 to perform well regionally, though the poor global A_T performance and the relatively good performance in the Amazon plume were surprising. We include HG2 in the comparison mainly to illustrate how this methodology could be used to compare model data with quite different input sources such as satellite data. Our results provide a potentially useful dataset (including uncertainty information) to evaluate and challenge Earth system model outputs.

686

687 5. Conclusions

We demonstrate that satellite SSS and SST data are, in conjunction with empirical algorithms, able to successfully reproduce both A_T and C_T in four regions (globally, the Caribbean, the Amazon and the low salinity Amazon) as well as or better than *in situ*-derived (re-analysed) SSS and SST using the same empirical algorithms, or a global Earth system model dataset, with the advantage that satellite datasets are acquired daily, on average, with synoptic coverage.

The ability to derive key surface carbonate system parameters from satellite observed SSS and SST offers the potential for quantifying natural variability, as well as monitoring the present state of these important parameters through space and time. Satellite sensors provide a significant advantage over traditional *in situ* derived climatologies because of the ability to provide synoptic and frequent observations of global oceans. Critically, many of the satellites that provide these data are already in operation, hence historic satellite sensor datasets could

700 be used with these algorithms to elucidate changes over longer periods of time. These 701 satellite methods should not replace ongoing in situ measurements, but should complement 702 and enhance them by providing observations in periods where there are gaps in both time and 703 space. Ongoing in situ data are essential to improve our ability to exploit satellite data, for example through enhanced parameterization of the algorithms. Satellites are also only able to 704 705 measure surface waters, and are unable to measure under ice. These gaps must be filled with 706 in situ data. Similarly, the evolving nature of the carbonate system due to anthropogenic forcing means that it is likely that these empirical algorithms will need to be periodically re-707 708 trained to maintain their performance. Hence the algorithms and methods utilized are useful 709 for studying seasonal and inter-annual variations and episodic events, but may not be suitable 710 for resolving longer-term trends.

711

The assessment presented here, which represents a significant effort and extensive analysis,
provides the baseline performance against which any future algorithm re-training or recalibration attempts can be compared.

715

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725 Tables

Table 1: Summary of algorithms, their dependencies and the region for which they were originally developed. A_T = Total Alkalinity, C_T = Dissolved Inorganic Carbon; SSS = Sea Surface Salinity, SST = Sea Surface Temperature, DO = Dissolved Oxygen, N = nitrate, Si = silicate, P = phosphate.

Product	Name	Dependencies	Reference	Region
A _T	TS13	SSS, N	(Takahashi and Sutherland 2013)	Global
\mathbf{A}_{T}	L06	SSS, SST	(Lee et al. 2006)	Global
A _T	S13	SSS, SST, DO, Si, P	(Sasse et al., 2013)	Global
A _T	S13g	SST, SSS, DO, Si, P	(Sasse et al., 2013)	Global
\mathbf{A}_{T}		SSS	(Lefèvre et al. 2010)	APR
\mathbf{A}_{T}		SSS	(Cai et al. 2010)	GCR, APR
CT	L00	SSS, SST, N	(Lee et al. 2000)	Global
C_T	S13	SST, SSS, DO, N, Si, P	(Sasse et al., 2013)	Global
C_T	S13g	SST, SSS, DO, N, Si, P	(Sasse et al., 2013)	Global
C_{T}		SSS	(Lefèvre et al. 2010)	APR
C_{T}		SSS	(Bonou et al. 2016)	APR

730

731

Table 2: Datasets used as inputs to the empirical algorithms. SSS = sea surface salinity, SST
= sea surface temperature, DO = dissolved oxygen.

	Туре	Name	Time period	References
SSS	Satellite	SMOS (CATDS v2)	2010 - 2014	(Reul and Team 2011)
SSS	Satellite	Aquarius	2011 - 2014	(Le Vine et al. 2014)

SST	Satellite	ESA SST CCI	1992 - 2010	(Merchant et al. 2012)
SSS, SST	Re-analysis	CORA v4.0	1990 - 2012	(Cabanes et al. 2013)
SSS, SST, DO, N, P, Si	Climatology	WOA	1970 - 2012	(Garcia et al. 2014a; Garcia et al. 2014b; Locarnini et al. 2013; Zweng et al. 2013)

Table 3: *In situ* carbonate chemistry datasets used for evaluating the outputs. All datasets for
each variable were combined into one dataset that was averaged monthly on a 1°x1° grid.
The Bhadury et al. coastal data are from a sampling station located on the coast of India at
21° 40' 40.6" N, 88° 9' 19.2"E, shown in Figure 1 of Choudhury et al. (2015) (Station 3).
The Findlay et al. research cruise data are from cruises off the Svalbard and Greenland
coasts, 78° 53'-59' N, 11° 42'-12° 27' E and 70° 14-49' N, 22° 4-32'W respectively.

	Dataset name	Time period	References
A_T, C_T	GLODAPv2	1970 - 2013	(Olsen et al. 2016)
A_T, C_T	OWS Mike	2001 - 2007	(Findlay et al. 2008)
\mathbf{A}_{T}	Bhadury et al. coastal data	2014	(Choudhury et al. 2015)
A_T, C_T	Findlay et al. research cruise	2012 - 2014	[Findlay pers. comm.]

Table 4: Coverage, RMSDe and bias of the lowest RMSDe output for each SSS source in
each region and carbonate parameter. Note that coverage is compared to all possible
matchups, so recent SSS sources such as satellites have relatively low coverage.

SSS INPUT	COVERAGE (%)	RMSDe (µmol kg ⁻¹)	BIAS (µmol kg ⁻¹)
GLOBAL A _T (N=6019) In situ SD for comparison		81	
SSS_CORA	88	17	0
SSS_AQUARIUS	4	17	3
SSS SMOS	6	17	-5
HG2	100	32	-17
SSS_CORA_CLIM	96	17	-2
SSS_WOA_CLIM	96	17	0

SSS_SMOS_CLIM	94	18	1
SSS_AQUARIUS_CLIM	93	18	-5
HG2_CLIM	100	31	-16
G CARIB AT (N=55) In situ SD for comparison		13	
SSS_CORA	96	17	3
SSS_AQUARIUS	13	19	-4
SSS_SMOS	13	20	-4
HG2	100	50	50
SSS_CORA_CLIM	100	17	-4
SSS_WOA_CLIM	100	17	3
SSS_SMOS_CLIM	100	17	3
SSS_AQUARIUS_CLIM	100	19	2
HG2_CLIM	100	48	50
AMAZON A _T (N=108) <i>In situ</i> SD for comparison		68	
SSS_SMOS	31	58	1
SSS_AQUARIUS	12	58	17
SSS_CORA	78	59	10
HG2	100	75	43
SSS_CORA_CLIM	100	57	-1
SSS_SMOS_CLIM	100	59	-2
SSS_AQUARIUS_CLIM	100	60	1
SSS_WOA_CLIM	100	60	-6
HG2_CLIM	100	73	41
AMAZON S<35 A _T (N=15) In situ SD for comparison		115	
SSS_SMOS	20	132	124
SSS_CORA	20	132	125
SSS_AQUARIUS	87	132	26
HG2	100	172	128
SSS_CORA_CLIM	100	132	25
SSS_AQUARIUS_CLIM	100	133	-19
SSS_WOA_CLIM	100	135	24
SSS_SMOS_CLIM	100	136	20
HG2_CLIM	100	166	121
BENGAL A _T (N=23) <i>In situ</i> SD for comparison		16	
SSS_CORA	96	11	-3
HG2	100	52	77
SSS_CORA_CLIM	100	10	-3
SSS_SMOS_CLIM	100	10	3
SSS_WOA_CLIM	100	11	5
SSS_AQUARIUS_CLIM	100	11	-2
HG2_CLIM	100	55	83
GLOBAL C _T (N=6689) In situ SD for comparison		69	
SSS_CORA	90	30	-9
SSS_SMOS	6	30	-13
SSS_AQUARIUS	3	30	23
HG2	100	33	-13
SSS_WOA_CLIM	99	29	-8

SSS_CORA_CLIM	99	29	-8
SSS_AQUARIUS_CLIM	96	30	21
SSS_SMOS_CLIM	97	31	22
HG2_CLIM	100	34	-17
G CARIB C _T (N=53) <i>In situ</i> SD for comparison		18	
SSS_CORA	96	19	14
SSS_SMOS	13	19	3
SSS_AQUARIUS	13	19	4
HG2	100	42	52
SSS_WOA_CLIM	100	19	9
SSS_CORA_CLIM	100	19	10
SSS_SMOS_CLIM	100	19	10
SSS_AQUARIUS_CLIM	100	19	8
HG2_CLIM	100	36	45
AMAZON C _T (N=155) In situ SD for comparison		53	
SSS_CORA	85	45	3
SSS_SMOS	21	45	3
SSS_AQUARIUS	8	48	0
HG2	100	57	33
SSS_CORA_CLIM	100	45	0
SSS_SMOS_CLIM	100	45	0
SSS_WOA_CLIM	100	45	-2
SSS_AQUARIUS_CLIM	100	46	-1
HG2_CLIM	100	53	30
AMAZON S<35 C _T (N=17) In situ SD for comparison		96	
SSS_SMOS	18	109	100
SSS_AQUARIUS	18	109	108
SSS_CORA	94	109	45
HG2	100	132	118
SSS_SMOS_CLIM	100	109	3
SSS_CORA_CLIM	100	109	44
SSS_AQUARIUS_CLIM	100	111	21
SSS_WOA_CLIM	100	111	45
HG2_CLIM	100	125	108
BENGAL C _T (N=24) <i>In situ</i> SD for comparison		10	
SSS_CORA	96	19	16
HG2	100	36	51
SSS_CORA_CLIM	100	18	-12
SSS_WOA_CLIM	100	18	-11
SSS_SMOS_CLIM	100	19	-14
SSS_AQUARIUS_CLIM	100	20	-17
	100	34	48

Table 5: Selected importances of exclusions for each carbonate parameter and region. A
source of SSS or SST can be monthly (M), climatological (C) or all (no prefix). Importances
are the percentage increase in RMSDe as a result of excluding all the listed inputs or

- algorithms. Only exclusions mentioned in the text are listed here, more complete lists can be
- 753 found in (Land et al., 2019).

EXCLUSIONS

(GLOBAL AT) TS13,L06,S13g TS13,L06,S13g,S13 CORA,M SMOS,M Aquarius,WOA SSS CORA,SMOS,M Aquarius,WOA SSS	
(G CARIB A _T) CORA,WOA,C SMOS SSS TS13,L06,S13g,Cai10 TS13,L06,S13g,Cai10,S13 CORA,WOA,C Aquarius,C SMOS SSS CORA,WOA,Aquarius,C SMOS SSS	
(AMAZON AT) TS13,L06,S13,S13g TS13,L06,S13,S13g,Cai10 SMOS,CORA,M Aquarius SSS TS13,L06,S13,S13g,Cai10,Lefevre10 SMOS,CORA,Aquarius SSS	
(AMAZON S<35 A _T) M SMOS,M Aquarius SSS,M CCI SST M SMOS,Aquarius SSS,M CCI SST SMOS,Aquarius SSS,M CCI SST M SMOS,Aquarius,CORA SSS TS13,L06,S13,S13g,Cai10,Lefevre10	
(BENGAL AT) C CORA SSS C CORA,C SMOS SSS C CORA,C SMOS,WOA SSS TS13,L06,S13 TS13,L06,S13,S13g CORA,C SMOS,WOA SSS	
(GLOBAL CT) L00 L00,S13g L00,S13g,S13 CORA,WOA,M SMOS SSS CORA,WOA,M SMOS,M Aquarius SSS CORA,WOA,Aquarius,M SMOS SSS	
(G CARIB CT) L00,S13 L00,S13,S13g SMOS,CORA,WOA,M Aquarius SSS	
(AMAZON C _T) L00,S13,Bonou16,Lefevre10 L00,S13,Bonou16,Lefevre10,S13g SMOS,CORA,WOA SSS SMOS,CORA,C Aquarius,WOA SSS	

(AMAZON S<35 C_T)

L00,S13,Bonou16,Lefevre10 L00,S13,Bonou16,Lefevre10,S13g

IMPORTANCE NOTES (%)

3.1 85 3.0 4.1	Only leaves S13,HG2 Only leaves HG2 Only leaves C SMOS,C Aquarius Only leaves C Aquarius
13 2.9 286 16 18	Only leaves M SMOS,Aquarius Only leaves S13,HG2 Only leaves HG2 Only leaves M SMOS,M Aquarius Only leaves M SMOS
2.6 4.4 4.0 26 5.1	Only leaves Lefevre10,HG2 Only leaves C Aquarius,WOA SSS Only leaves HG2 Only leaves WOA SSS
2.5 3.2	All monthly satellite data
4.6 2.9 26	Only leaves HG2
2.2 5.1 6.4 3.7 517 8.1	Only leaves M CORA,C Aquarius Only leaves S13g,HG2 Only leaves HG2 Only leaves C Aquarius
3.6 5.3	
14	Only leaves HG2
3.6 4 4	Only leaves C SMOS C Aquarius
7.7	Only leaves C SMOS
73	Only leaves S13g and HG2
90 3.9	Only leaves HG2 Only leaves C Aquarius
2.1	Only leaves S13g and HG2
19	Only leaves HG2
3.6	Only leaves Aquarius
/.0	Only leaves M Aquarius
2.2	Only leaves S13g and HG2
15	Only leaves HG2

SMOS,Aquarius SSS,M CCI SST SMOS,Aquarius,CORA SSS,M CCI SST	2.6 4.9	Only leaves CORA,WOA SSS Only leaves WOA SSS
(BENGAL C _T)		
S13	2.1	
S13,S13g	9.9	
C CORA,WOA SSS	2.1	
L00,S13,S13g	83	Only leaves HG2
CORA,WOA SSS	3.6	-
CORA,C SMOS,WOA SSS	5.9	

755	Table 6: Testing the sensitivity of the output uncertainties to that of the satellite remote
756	sensing input data uncertainties using all global AT algorithms (TS13, Lee06, Lee00, S13 and
757	S13g) and exemplar uncertainties from the literature (for SST, Merchant et al., (2014) gives
758	± 0.15 °C; for SSS, Boutin <i>et al.</i> , (2018) gives ± 0.2). The output uncertainties are given as a
759	percentage of a global value of 2000 μ mol kg ⁻¹ and the quoted values are the maximum open-
760	ocean values calculated for all data within latitudes <±60°.

Algorithm	Uncertainty in A _T due to SSS (%)	Uncertainty in A _T due to SST (%)
TS13	<±0.8	N/A
Lee06	<±0.7	<±0.2
Lee00	<±0.9	<±0.2
S13	<±0.6	<±0.1
S13g	<±0.6	<±0.1





Figure 1: Estimated regional weighted RMSD (RMSDe) for each SSS source. Data are grouped by region, then by whether the input data are climatological (left group) or monthly (right group), then by SSS source. All regional output s using a given SSS source are considered, and the wide bar shows the lowest RMSDe of these, the half-width bar shows the median RMSDe and the thin bar shows the highest RMSDe. SSS sources in each group are shown in order of global lowest RMSDe. (A) A_T results; (B) C_T results.



Figure 2: Comparison of A_T estimated using monthly satellite SSS with *in situ* measured A_T . (A) global; (B) Amazon plume; (C) Bay of Bengal using climatological satellite SSS; (D) Greater Caribbean. The algorithm is (Takahashi et al. 2013) with climatological WOA nitrate. Red crosses use SMOS SSS, blue plusses use Aquarius. Points with down-pointing triangles have depth less than 500 m, those with up-pointing triangles are less than 300 km from the nearest coast. Regressions use all data.



Figure 3: Comparison of C_T estimated using monthly satellite SSS with in situ measured C_T . (A) global; (B) Amazon plume; (C) Bay of Bengal using climatological satellite SSS; (D) Greater Caribbean. The algorithm is (Lee et al. 2000) with climatological WOA SST and nitrate. Red crosses use SMOS SSS, blue plusses use Aquarius. Points with down-pointing triangles have depth less than 500 m, those with up-pointing triangles are less than 300 km from the nearest coast. Regressions use all data.



Figure 4: Comparison of A_T and C_T estimated from CORA (interpolated *in situ*) SSS with *in situ* measured values in the Amazon plume. (A) A_T comparison using climatological CORA SSS; (B) C_T comparison using climatological CORA SSS; (C) A_T comparison using monthly CORA SSS; (D) C_T comparison using monthly CORA SSS. The A_T algorithm is (Takahashi et al. 2013) with climatological WOA nitrate, and the C_T algorithm is (Lee et al. 2000) with climatological CORA SST and climatological WOA nitrate. Points with down-pointing triangles have depth less than 500 m, those with up-pointing triangles are less than 300 km from the nearest coast. Regressions use all data.



Figure 5: Comparison of satellite and CORA SSS with *in situ* measured SSS in the Amazon plume. (A) monthly SMOS (red crosses) and Aquarius (blue plusses); (B) climatological SMOS and Aquarius; (C) monthly CORA; (D) climatological CORA. Points with down-pointing triangles have depth less than 500 m, those with up-pointing triangles are less than 300 km from the nearest coast. Regressions use all data.



Figure 6: Time series of Amazon plume discharge and averaged satellite observations between 2010 and 2016. Monthly observations were average over the area 0°-15° N,

 45° - 62° W. Dashed black lines are climatological discharge at the Obidos gauge, red use SMOS SSS and blue use Aquarius SSS. In months containing both SMOS and Aquarius data, only cells with valid data in both are used. (A) monthly SMOS and Aquarius SSS; (B) climatological CORA (orange) SST; (C) A_T using the TS13 algorithm and WOA nitrate, with monthly SMOS and Aquarius SSS; (D) C_T using the L00 algorithm, CORA SST climatology and WOA nitrate, with monthly SMOS and Aquarius SSS.



Figure 7: Aquarius derived synoptic scale observations of A_T in µmol kg⁻¹ for the Amazon Plume between August 2011 and June 2015 using the TS13 algorithm and WOA nitrate, with monthly SMOS and Aquarius SSS: (a) A_T in August 2011 showing the bifurcation of the plume; (b) Hovmöller time series plot for 55° W; (c) Hovmöller time series plot for 52° W and (d) Hovmöller time series plot for 45° W.



Figure 8: Synoptic scale Aquarius (A) and SMOS (B) derived A_T in µmol kg⁻¹ for April 2012 using the TS13 algorithm and WOA nitrate, with monthly SMOS and Aquarius SSS. *In situ* observations collected in April and May 2012 from the GLODAPv2 dataset are overlaid as circles. The May 2012 *in situ* observations are all within the offshore region (latitude >20° N).



Figure 9: Synoptic scale Aquarius (A) and SMOS (B) derived C_T in µmol kg⁻¹ for April 2012

using the L00 algorithm, CORA SST climatology and WOA nitrate, with monthly SMOS and Aquarius SSS. *In situ* observations collected in April and May 2012 from the GLODAPv2 dataset are overlaid as circles. The May 2012 *in situ* observations are all within the offshore region (latitude $>20^{\circ}$ N).

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782	Supporting information/non-print material
783	Supporting Information: Land et al., (2019) and landetal-SupportingInformation.docx
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Supporting Information for

Optimum satellite remote sensing of the marine carbonate system using empirical algorithms in the Global Ocean, the Greater Caribbean, the Amazon Plume and the Bay of Bengal

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Contents of this file

Text S1 and S2 Figure S1 Datasets S1 to S23 References

Introduction

Supporting information is provided on the details of the algorithms used in the analyses (Text S1) along with the input data nomenclature for the datasets (Text S2). The datasets themselves are provided in three versions within (Land et al., 2019) which is available at https://doi.pangaea.de/10.1594/PANGAEA.898115: the first uses all data; the second excludes grid cells containing areas with depth less than 500 m, and the third is the same as the second, but also excludes grid cells containing areas closer than 300 km to any coast. The matchup data used and outputs at each matchup are provided in Datasets S1 to S5 (.csv files). Summary statistics for each output are provided in Datasets S6 to S10 (.csv files). Data pertaining to the method of scoring outputs are provided in Datasets S16 to S20 (netCDF files). The effects of excluding algorithms and/or data sources are shown in Datasets S21 (all combinations) and S22 (selected combinations) (.csv files). Results of the comparison of total alkalinity (A_T) and dissolved inorganic carbon (C_T) retrievals are provided in Dataset S23 (.csv file).

Text S1. Algorithm details.

(Lee et al. 2006) A_T algorithms (L06):

Regionally variable slope and intercept parameters (see (Lee et al. 2006) for details) for the following algorithm:

 $A_T = a + b(SSS - S) + c(SSS - S)^2 - d(SST - T) + e(SST - T)^2,$

where *S* and *T* are salinity and temperature variables with fixed values for a given region. Temperature and salinity ranges of validity in each region are specified in LeeEtAl2006.nc, included with the software.

(Takahashi and Sutherland 2013) A_T algorithms (TS13):

Regionally variable slope and intercept parameters (See (Takahashi and Sutherland 2013) for details) for the following algorithm:

 $A_T = (A_0 \times SSS + A_1) - NO_3$

Note that there is a misprint in Table 1 of (Takahashi and Sutherland 2013) – the intercept of Region 25 Antarctic (Pacific) should read -450.8 rather than 450.8, as shown in Figure 6 of (Takahashi and Sutherland 2013).

Salinity ranges of validity in each region are specified in TakahashiSutherland.nc, included with the software.

(Sasse et al. 2013) A_T algorithms (S13 and S13g):

Regionally variable plus global slope and intercept parameters (See (Sasse et al. 2013) for details) for the following algorithm:

 $A_T = a + bSST + cSSS + dSSS^2 + eDO + fSi + gPO_4 + interaction terms.$

We found no information in (Sasse et al. 2013) about data ranges, so these algorithms are applied to all data.

(Cai et al. 2010) and (Lefèvre et al. 2010) A_T algorithms:

Simple linear relationships of A_{τ} with SSS for the Greater Caribbean (Cai et al. 2010 only) and Amazon Plume regions (see (Cai et al. 2010; Lefèvre et al. 2010) for details).

The salinity range of applicability of (Cai et al. 2010) is 32.9 to 37.8 in the Greater Caribbean and 23.8 to 38.1 in the Amazon Plume, and that of (Lefèvre et al. 2010) is 17 to 37.

(Lee et al. 2000) C_T algorithms (L00):

Regionally variable slope and intercept parameters (See (Lee et al. 2000) for details) for the following algorithm:

 $nC_{T} = a + b \times SST + c \times SST^{2} + d \times NO_{3}$ $nC_{T} = C_{T} \times \frac{35}{SSS}$

Between 30°N and 30°S, (Lee et al. 2000) increase nC_T by 1 umol kg⁻¹ per year.

Temperature and salinity ranges of validity in each region are specified in LeeEtAl2000.nc, included with the software.

(Sasse et al. 2013) C_T algorithms (S13 and S13g):

Regionally variable plus global slope and intercept parameters (See (Sasse et al. 2013) for details) for the following algorithm:

 $C_T = a + bSST + cSSS + dDO^2 + eNO_3 + fSi + gPO_4 + interaction terms.$

(Sasse et al. 2013) include a calculated correction for the anthropogenic increase in C_T with a global average of 1 umol kg⁻¹ per year. Here we use the global average value for simplicity and consistency with (Lee et al. 2000).

We found no information in (Sasse et al. 2013) about data ranges, so these algorithms are applied to all data.

(Lefèvre et al. 2010) and (Bonou et al. 2016) C_T algorithms:

Simple linear relationships of C_{T} with SSS for the Amazon Plume Region (see (Bonou et al. 2016; Lefèvre et al. 2010) for details). (Bonou et al. 2016) increase C_{T} by 0.9 umol kg⁻¹ per year. The salinity range of applicability of (Lefèvre et al. 2010) is 17 to 37, and that of (Bonou et al. 2016) is 0 to 38.3.

Text S2: Details of the input parameter nomenclature

Parameter names ending in "_CLIM" are monthly climatologies, i.e. 12 climatologies for January to December. All other names indicate multi-year monthly data. So an *in situ* measurement from January 2010 would be compared with the January part of _CLIM datasets, and the January 2010 part of all other datasets.

HG2 and HG2 CLIM:

The Met Office Hadley Centre, Hadley Global Environment Model 2 - Earth System (HadGEM2-ES) multi-year monthly dataset and monthly climatology.

SSS_WOA_CLIM, SST_WOA_CLIM, DO_WOA_CLIM, NITRATE_WOA_CLIM, SILICATE_WOA_CLIM and PHOSPHATE_WOA_CLIM:

World Ocean Atlas 2013 (WOA) monthly climatologies, spatially interpolated to 1°×1° (Garcia et al. 2014a; Garcia et al. 2014b; Locarnini et al. 2013; Zweng et al. 2013). Note that WOA nitrate is actually nitrate + nitrite.

SSS_SMOS and SSS_SMOS_CLIM: SMOS satellite SSS multi-year monthly datasets and monthly climatology.

SSS_AQUARIUS and SSS_AQUARIUS_CLIM: Aquarius satellite SSS multi-year monthly datasets and monthly climatology.

SSS_CORA, SSS_CORA_CLIM, SST_CORA and SST_CORA_CLIM:

Coriolis Ocean ReAnalysis database (version 4.0), which includes data from ARGO, the global network of moored buoys (including TAO/TRITON, PIRATA, RAMA buoys), underwater gliders (EGO), GTSPP, Ships of opportunity, sea mammals equipped with sensors, and other integrated datasets from CTDs, oceanographic cruises, etc. This database is output in two sets: _CORA_CLIM is the monthly climatology; and _CORA is the multi-year monthly dataset.

SST CCI and SST CCI CLIM:

Sea Surface Temperature Climate Change Initiative data archives from ESA's ATSR and AATSR.



Figure S1: Equivalent plots to that of Figure 1 in the main manuscript but with alternative depth and coastal masking. (A) repeat of Figure 1(A), A_T with minimum depth 500 m and minimum distance to coast 300 km masked; (B) repeat of Figure 1(B), C_T with minimum depth 500 m and minimum distance to coast 300 km masked; (C) A_T with minimum depth 500 m; (D) C_T with minimum depth 500 m; (E) A_T with no masking; (F) C_T with no masking.

Datasets introduction

In the following datasets, which are all available within Land et al., (2019). 'X' denotes one of three versions: " corresponds to all data, 'Depth500' to a minimum depth of 500 m, and 'Depth500Dist300' to a minimum depth of 500 m and a minimum distance to coast of 300 km. Each of the three versions is contained in its own directory.

Datasets S1 to S5 are .csv files containing all matchups in each region, including date and location, *in situ* A_T and C_T measurements and estimated uncertainties, all input datasets, estimates of A_T and C_T from all outputs, and the best available output estimates of A_T and C_T for each matchup (see main text).

- S1_GlobalAlgorithmMatchupsX.csv
- S2_GreaterCaribbeanAlgorithmMatchupsX.csv
- S3_AmazonPlumeAlgorithmMatchupsX.csv
- S4_AmazonPlumeLowSAlgorithmMatchupsX.csv
- S5_BayOfBengalAlgorithmMatchupsX.csv

Datasets S6 to S10 are .csv files containing statistics of all outputs in each region, including the carbonate system variable, algorithm, input datasets used, (MAD, RMSD using all available data, output score, RMSD estimated from output score, output and in situ mean and standard deviation, correlation coefficient), all items in brackets presented both unweighted and weighted, number of matchups, number of potential matchups, matchup coverage, RMSD after subtraction of linear regression, percentage reduction in RMSD due to subtraction of linear regression and weighted score divided by number of matchups (see main text for explanation of terms).

- S6_GlobalAlgorithmScoresX.csv
- S7_GreaterCaribbeanAlgorithmScoresX.csv
- S8_AmazonPlumeAlgorithmScoresX.csv
- S9_AmazonPlumeLowSAlgorithmScoresX.csv
- S10_BayOfBengalAlgorithmScoresX.csv

Datasets S11 to S15 are netCDF files containing error analyses of all outputs in each region, including the squared error of each output at each matchup, the weight of each squared error (1/squared uncertainty), weight * squared error, number of matchups available to each output, number of matchups available to each combination of two outputs, (score of each output in a given comparison of two outputs, overall output score and RMSD estimated from output score), all items in the last brackets presented both unweighted and weighted.

- S11_GlobalSquaredErrorsX.nc
- S12_GreaterCaribbeanSquaredErrorsX.nc
- S13_AmazonPlumeSquaredErrorsX.nc
- S14_AmazonPlumeLowSSquaredErrorsX.nc
- S15_BayOfBengalSquaredErrorsX.nc

Datasets S16 to S20 are netCDF files containing global maps of the data in Tables S4 to S9, showing the spatial distribution of the mean and standard deviation of each of: *in situ* data; output data; output data – *in situ* data and number of matchups. Regional files show the same maps, but only including data within the region.

S16_GlobalmapsX.nc S17_GreaterCaribbeanmapsX.nc S18_AmazonPlumemapsX.nc S19_AmazonPlumeLowSmapsX.nc S20 BayOfBengalmapsX.nc

Datasets S21 and S22 are .csv files containing the effect on estimated RMSD of excluding various combinations of algorithms and/or inputs for A_T and C_T in each region. For a given variable and region, the first line shows the algorithm, input data sources, estimated RMSD and bias of the output with lowest estimated RMSD. Subsequent lines show the effect of excluding combinations of algorithms and/or inputs, ordered first by the number of algorithms/inputs excluded (fewest first), then by effect on lowest estimated RMSD. So the first line(s) consist of the effects of excluding the best algorithm and each of the input sources to that algorithm, most important first. Each line consists of the item excluded, ratio of resulting estimated RMSD to original estimated RMSD, resulting bias and number of items excluded. Some exclusions are equivalent, for instance exclusion of WOA nitrate (the only nitrate source) is equivalent to excluding all algorithms using nitrate. Dataset S21 contains a comprehensive list of all possible exclusions, and so is rather hard to read and interpret. To mitigate this, Dataset S22 contains only those exclusion sets with effect greater than 1% and at least 0.1% greater than any subset of its exclusions.

S21_importancesX.csv S22_importances2X.csv

Dataset S23 is a .csv file containing like-for-like comparisons of RMSD between A_T and C_T in each region. Bear in mind that the RMSD shown here is not the same as the estimated RMSD (RMSDe in the main text) shown elsewhere.

S23_TA_DICcomparisonX.csv

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